



TextPSG: Panoptic Scene Graph Generation from Textual Descriptions

Chengyang Zhao¹ Yikang Shen² Zhenfang Chen² Mingyu Ding³ Chuang Gan^{2,4}

¹Peking University ²MIT-IBM Watson AI Lab ³UC Berkley ⁴UMass Amherst

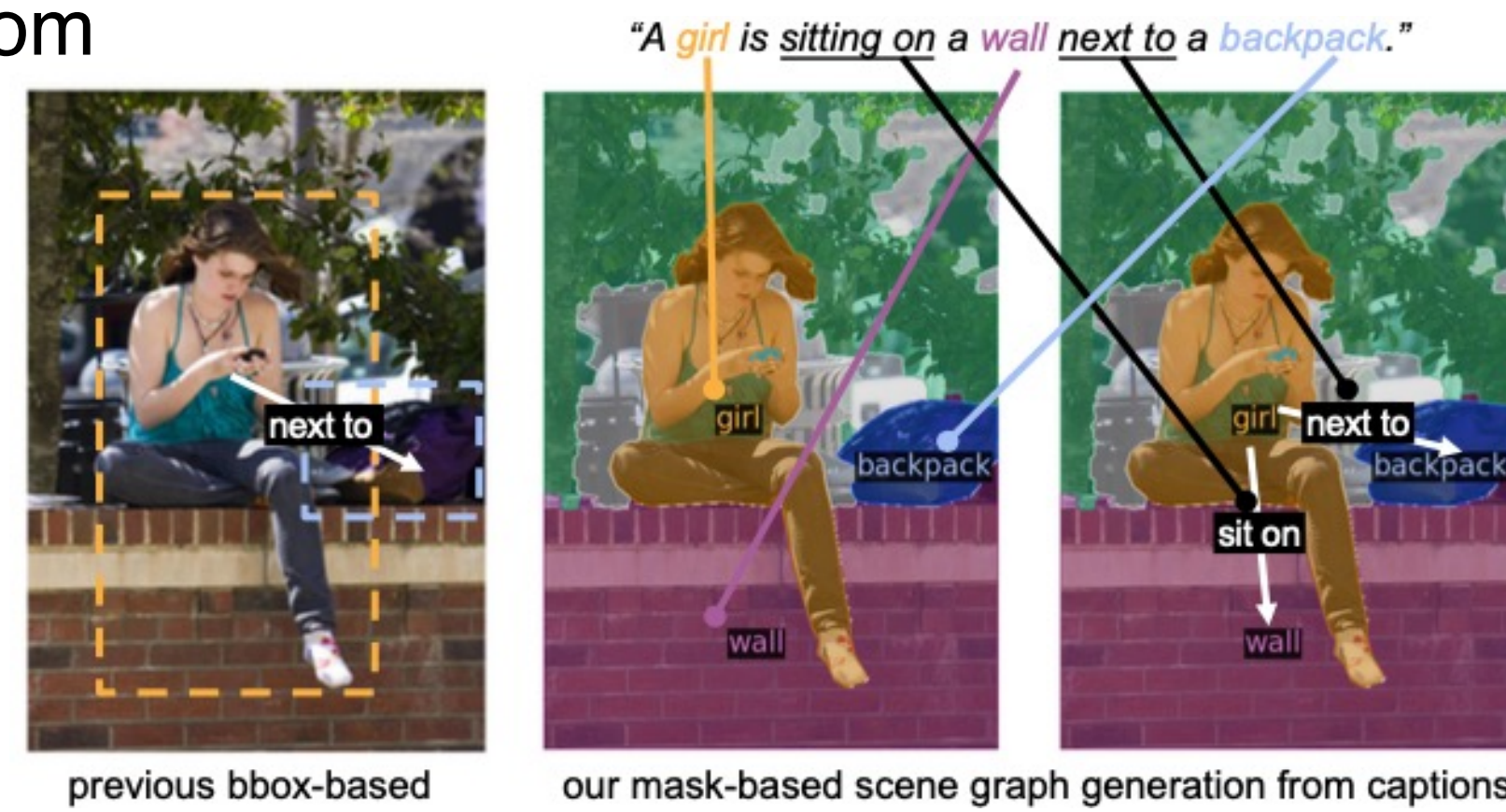


Motivation

Problem: Panoptic Scene Graph Generation from **Purely** Textual Descriptions (Caption-to-PSG)

“Purely” for Three Constraints:

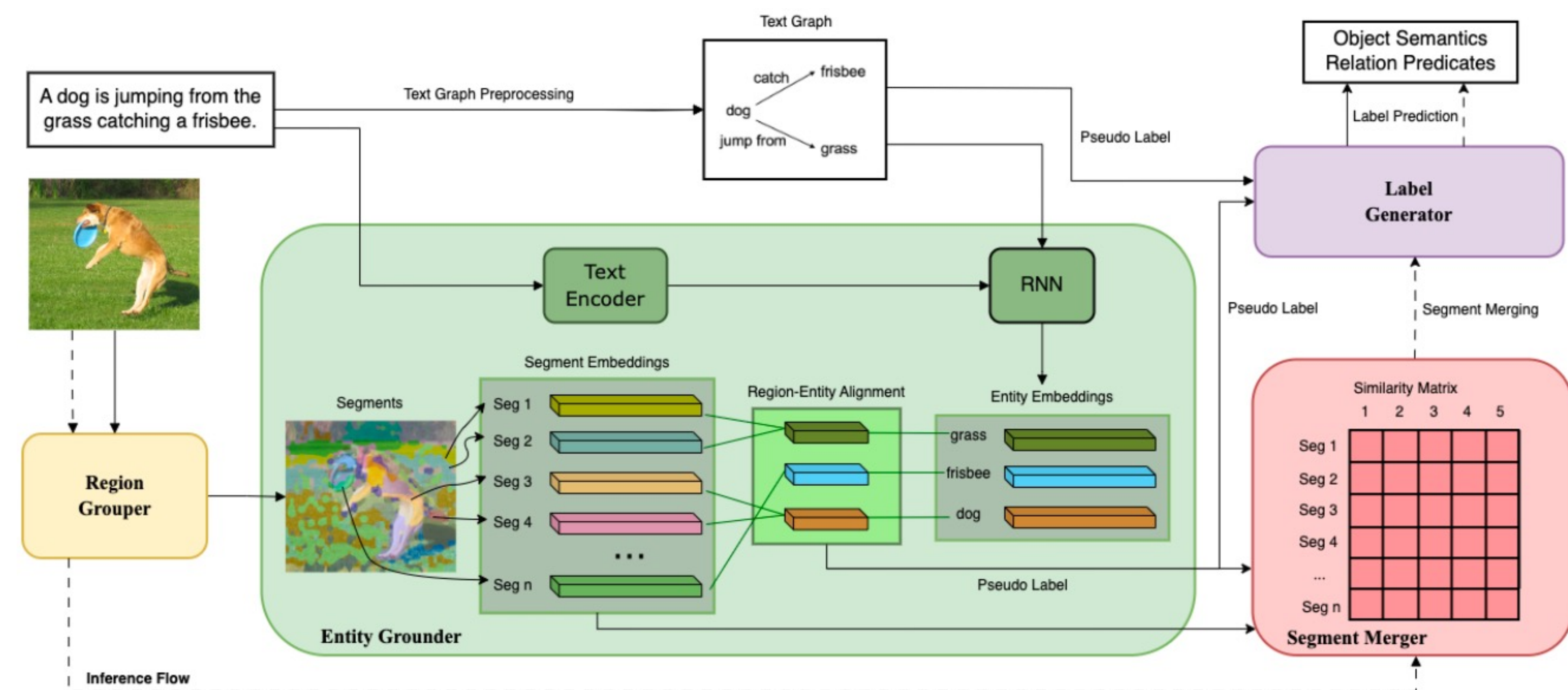
- No location priors
- No explicit region-entity links
- No pre-defined concept sets



Two Key Challenges:

- Learning to the ground entities in language onto the visual scene, developing the ability to perform partitioning and grounding purely from textual descriptions
- Learning the object semantics and relation predicates from textual descriptions, without pre-defined fixed object and relation vocabularies

Framework



Region Grouper: partitioning the image in a hierarchical way

Entity Grounder: grounding textual entities onto the image segments through a fine-grained contrastive learning strategy

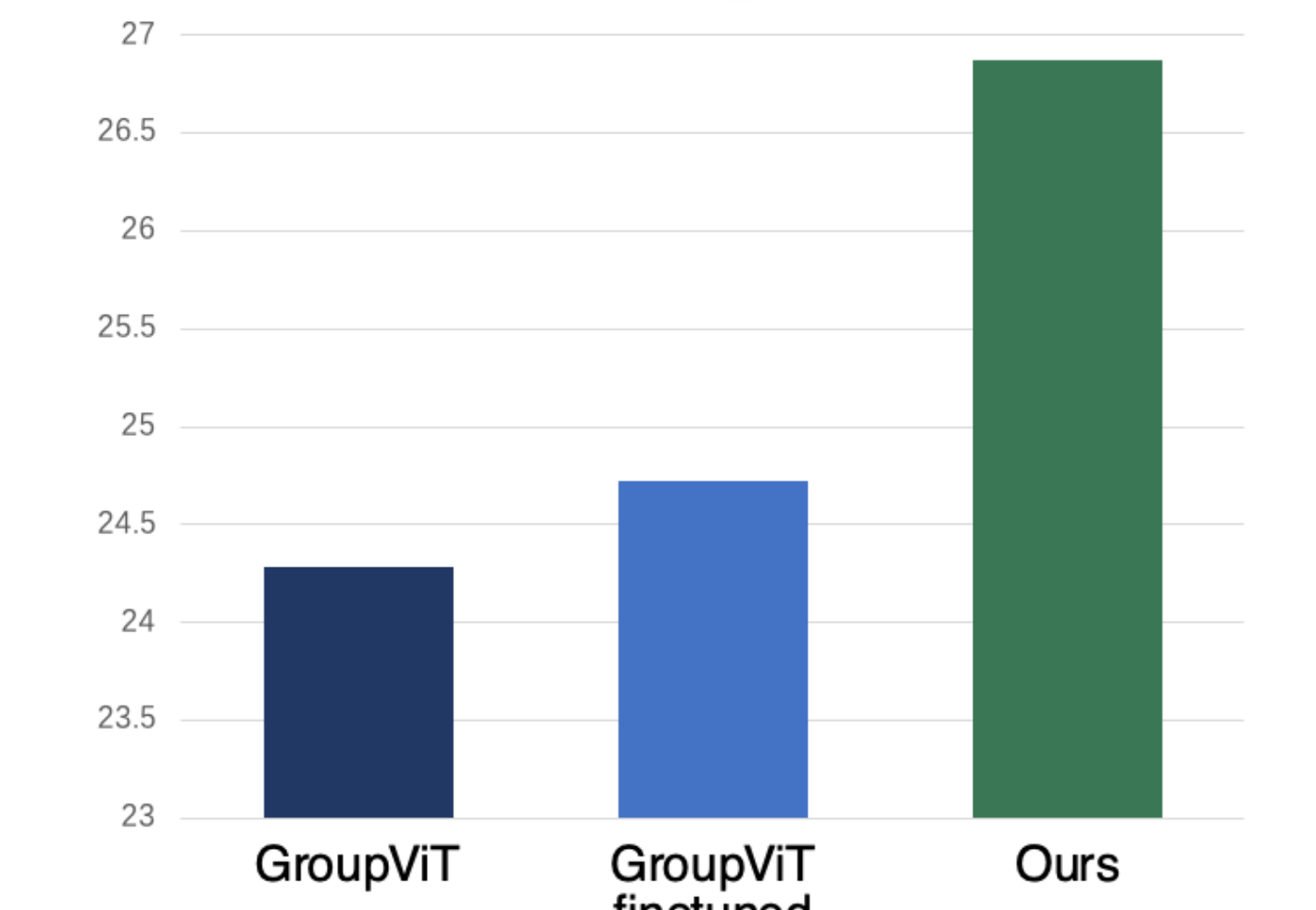
Segment Merger: leveraging the grounding results as explicit supervision to learn similarity matrices for inference-time merging

Label Generator: auto-regressive generation for prediction, leveraging pre-learned common sense from pre-trained language model, PET to better incorporate the common sense

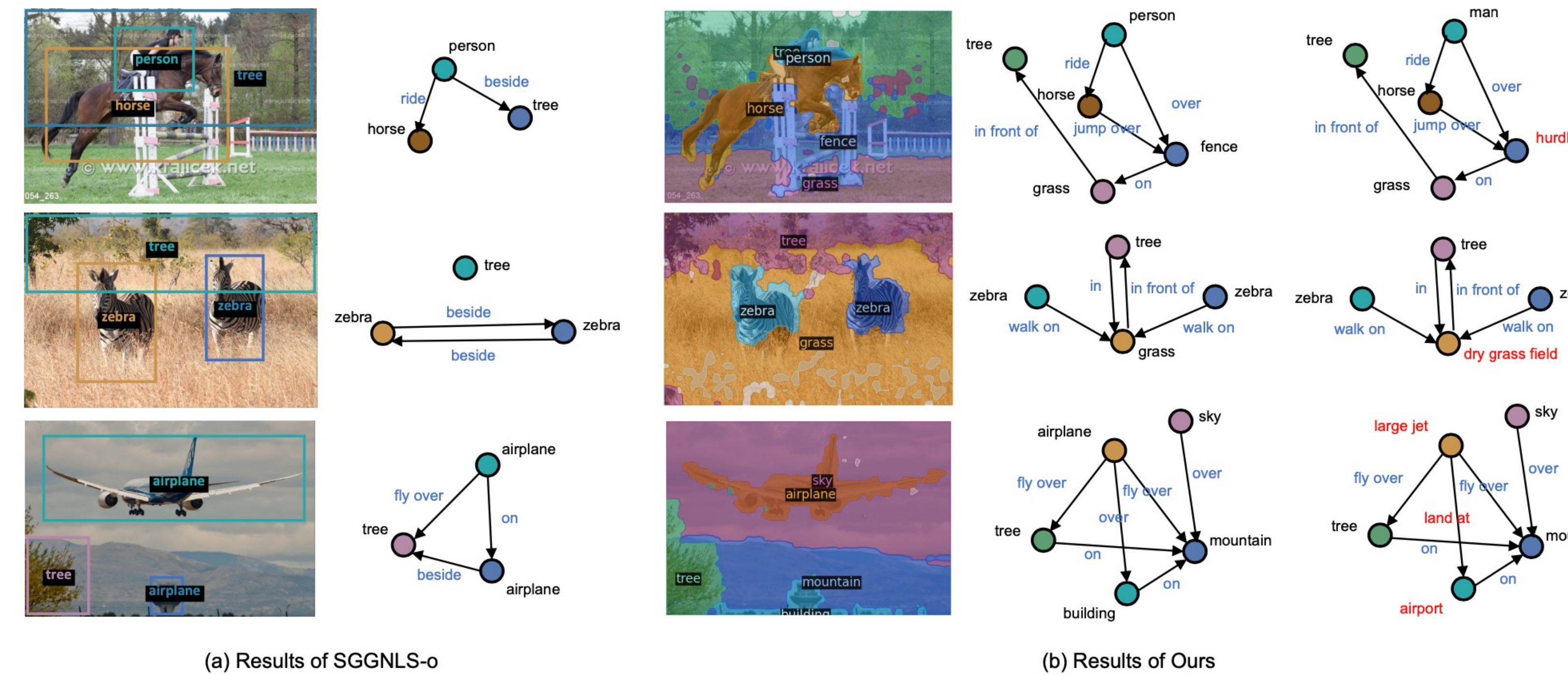
Quantitative Results

Method			Mode	PhrDet				SGDet			
Model	Proposal	Target		N3R50	N3R100	N5R50	N5R100	N3R50	N3R100	N5R50	N5R100
SGGNLS-c	Detector	✓	bbox	9.69	11.45	10.24	12.22	6.76	7.81	7.2	8.65
Random		✗	bbox	0.02	0.03	0.02	0.03	0.01	0.02	0.02	0.03
Prior	Selective	✗	bbox	0.04	0.07	0.05	0.07	0.03	0.06	0.05	0.07
MIL	Search	✗	bbox	1.97	2.18	2.04	2.61	1.2	1.35	1.56	1.97
SGCLIP		✗	bbox	3.02	3.45	3.38	3.71	2.13	2.3	2.39	2.7
SGGNLS-o	Detector	✗	bbox	6.2	6.79	6.92	7.93	3.96	4.21	4.53	5.02
Ours	–	✗	mask	8.28	9.16	9.06	10.51	3.32	3.63	3.71	4.18
Ours	–	✗	bbox	11.37	12.74	12.24	14.37	4.29	4.77	4.82	5.48

Text-supervised Semantic Segmentation



Qualitative Results



Ablation Studies

Stage	#Seg	Cut	PhrDet		SGDet	
			N3R100	N5R100	N3R100	N5R100
1	64	✗	10.73	11.39	3.18	3.51
1	64	✓	12.74	14.37	4.77	5.48
2	8	✗	9.24	11.03	3.53	4.35
2	8	✓	6.78	8.45	2.46	3.21

Ablation Study on the Segment Merger.

Label Prediction	Model	PhrDet		SGDet	
		N3R100	N5R100	N3R100	N5R100
Cls + WordNet	–	8.82	9.36	2.36	2.72
Gen	RNN	9.12	10.44	2.65	3.07
Gen w/o PET	BLIP [21]	2.33	2.58	0.45	0.6
Gen w/ PET	BLIP [21]	12.64	14.28	4.77	5.49

Ablation Study on the Label Generator.

OOD Robustness

Set	Model	Target	Mode	PhrDet		SGDet	
				N3R100	N5R100	N3R100	N5R100
ID	SGGNLS-c	✓	bbox	16.76	18.48	10.45	11.86
	SGGNLS-o	✗	bbox	11.55	13.64	7.13	8.47
	Ours	✗	mask	9.27	10.45	3.28	3.76
	Ours	✗	bbox	13.35	14.82	4.63	5.36
OOD	SGGNLS-c	✓	bbox	0	0	0	0
	SGGNLS-o	✗	bbox	0.05	0.06	0	0
	Ours	✗	mask	8.47	9.76	4.07	4.51
	Ours	✗	bbox	10.18	11.69	5.23	5.72



Project Page



GitHub Code

Scan the QR code for more information and to contact us!